IN THE CLAIMS

Please amend the claims as follows:

- 1. (original) Method for segmenting images into groups of segments, said segments being based on image features, with the steps of:
 - a) determining a group of pixels for segmenting,
 - b) determining for said group feature characteristics,
- c) determining from neighboring groups segment templates, said segment templates describing constant or continuous features within said neighboring groups,
- d) calculating for said group error values by comparing features of said group with features of said segment templates, and
- e) deciding to assign said group to one of said segment templates, or to create a new segment template based on said error values.
- 2. (original) Method according to claim 1, with the steps of determining for said image a plurality of groups and carrying out the steps a) e) for all groups of said image.
- 3. (original) Method according to claim 1, characterized in that said segment templates are determined spatially and/or temporally.

- 4. (original) Method according to claim 1, characterized in that scanning said groups of pixels for said segmentation is done memory matched.
- 5. (original) Method according to claim 1, characterized in that said decision to assign said group to one of said segment templates, or to a newly created segment template is based on threshold values.
- 6. (original) Method according to claim 1, characterized in that said features are based on chrominance, and/or luminance values, statistical derivatives of pixels, histograms, co-occurrence matrices and/or fractal dimensions.
- 7. (original) Method according to claim 1, characterized in that said segment templates comprise an average luminance and chrominance span of said pixels.
- 8. (original) Method according to claim 2, characterized in that said segment templates comprise at least one histogram.
- 9. (original) Method according to claim 3, characterized in that said segment templates comprise motion models.

- 10. (original) Method according to claim 1, characterized in that said segment templates comprise image position information.
- 11. (original) Device for calculating image segmentation according to claim 1 comprising:
- grouping means for grouping pixels of images into groups,
- extracting means for extracting feature characteristics from said groups,
- storing means for storing segment templates of neighboring groups,
- comparing means for comparing said extracted features with features of said segment templates,
- decision means for assigning said group of pixels to one of said segment templates or to create a new segment template based on error values determined between said extracted features and features of said segment templates.
- 12. (currently amended) Use of a method according to claim 1—or a device according to claim 11 in image and/or video processing, medical image processing, crop analysis, video compression, motion estimation, weather analysis, fabrication monitoring, and/or intrusion detection.